# Exercises

## Instructions

There are two exercices.

Most of exercice 1 answer is a program written by completing the templates from the companion archive http://cambium.inria.fr/~maranget/MPRI/EX021.tgz.

Answers should be submitted by email to Luc.Maranget@inria.fr before Monday February 14, noon. Solution to exercice 1 should compile with provided Makefile — make all for 1.1 and make c11 for 1.3.

### 1 Semaphores

A semaphore is an old fashioned synchronisation primitives that generalises the mutex: the semaphore is given a *capacity* and at most capacity threads can be in critical section simultaneously. Hence, a mutex is a semaphore with capacity 1.

For historical reasons semaphore lock is called "wait" and semaphore unlock is called "post".

Important: Code template for this exercice is available in directory semaphore from the companion archive.

#### 1.1 Coding a semaphore

Given a semaphore s initialised to capacity c, critical sections are defined from a call to wait\_semaphore (s) (analog of lock\_mutex) to post\_semaphore (s) (analog of unlock\_mutex). The semaphore uses an internal counter nfree to count the number of threads allowed to enter critical section. The counter is initialised to c at semaphore creation time, then:

- wait\_semaphore (s) checks that nfree is non-null and decrements it. If nfree is null, the thread suspends.
- post\_semaphore (s) increments nfree and release waiting threads.

One may write a semaphore with a mutex (to protect the modifications of nfree) and a condition variable (to wait on). Complete the following code:

/\* Signature of mutex and condition variable primitives \*/

```
pthread_mutex_t *alloc_mutex(void) ;
void free_mutex(pthread_mutex_t *p) ;
void lock_mutex(pthread_mutex_t *p) ;
void unlock_mutex(pthread_mutex_t *p) ;
pthread_cond_t *alloc_cond(void) ;
void free_cond(pthread_cond_t *p) ;
void wait_cond(pthread_cond_t *c, pthread_mutex_t *m) ;
void signal_cond(pthread_cond_t *c) ;
void broadcast_cond(pthread_cond_t *c) ;
```

```
/* Semaphore structure */
typedef struct {
   volatile int nfree ;
   pthread_mutex_t *mutex ;
   pthread_cond_t *cond ;
} semaphore_t ;

void free_semaphore(semaphore(int capacity) { ... }
void free_semaphore(semaphore_t *p) { ... }
void wait_semaphore(semaphore_t *p) { ... }
```

#### **1.2** Semaphore usage

We consider nprocs threads running function T1 below, with argument described by ctx\_t below:

```
typedef struct {
  int size ;
  pthread_barrier_t *b ;
  semaphore_t *sem ;
} common_t ;
typedef struct {
  int id ;
  common_t *common ;
} ctx_t ;
void *T1(void *_p) {
  ctx_t *p = p;
common_t *q = p->common ;
  for (int k = q->size-1 ; k >= 0 ; k--) {
    wait_semaphore(q->sem) ;
    printf("+") ;
    printf("-");
    post_semaphore(q->sem) ;
    wait_barrier(q->b) ;
    if (p->id == 0) printf("\n") ;
    wait_barrier(q->b) ;
  }
  return NULL ;
}
```

With a semaphore of capacity 2,  $q \rightarrow size = 1$  and nprocs == 4. Classify the following outputs as legal or illegal, giving a short explanation in each case:

 1. ++--+- 

 2. +++-+-- 

 3. -+-+-++

 4. +-++-+ 

 5. ++++++++

#### 1.3 C11 coding

Write the same program using C11 standard primitives. To that aim, you may need:

- Documentation, see for instance https://en.cppreference.com/w/c/atomic and https://en.cppreference.com/w/c/thread.
- A C11 compiler and standard library. On Linux, if your distribution defaults are not sufficient (as it is the case on Ubuntu 18.04 LTS for instance), you can install the musl-tools package and use the musl-gcc compiler.

The companion archive contains a template sem11.c, with missing parts shighlighted by TODO comments.

# 2 Sequentially consistent or not?

The following small programs are written in pseudo-C. Following our usual conventions x and y are shared memory locations, while r0 and r1 are registers. Moreover, \*x = 1 is a store; while r0 = \*x is a load. Shared locations and registers hold zero as initial value. By definition, a *behaviour* is a choice of final values

Test 1	Test 2	
TO   T1	TO   T1	
*x = 2   r0 = *y *y = 1   *x = 1	*x = 2   *x = 1 *y = 1   r0 = *y	
Observe x,r0	Observe: x,r0	
Test 3	Test 4	
TO   T1	TO   T1	
*x = 1   *y = 1 r0 = *y   r1 = *x	*x = 1   *y = 1 r0 = *x   r1 = *y	
Observe r0,r1	Observe r0,r1	

Figure 1: Four small progra	ms
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for some observed locations. That is, shared locations x and r0 for Test 1 and Test 2; registers r0 and r1 for Test 3 and Test 4.

We consider *valid* behaviours, *i.e.* behaviours that result from executions such that each load of a memory cell reads a value written by a store to the same memory cell or the initial value zero. List all valid behavours of the four tests, identifying sequentially consistent (SC) behaviours.