Data races in Java and static analysis

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Outline

Concurrency in Java

 Static Detection of dataraces
 lock-based typing Boyapati, Lee & Rinard

> Points-to analysis : Naik & Aiken (Points-to analysis + Type and effect system)

Conclusion and ongoing work

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Concurrency model

• Thread-based concurrency : shared memory (fields of shared objects)

Iexically scoped locking construct :

Preemptive scheduling

 $synchronized(x)\{\ldots\}$

(Interleaving semantics)

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Interleaving semantics

$$\begin{array}{c|c} (\text{small step}) & \text{interleaving semantics} \\ \text{sequential semantics} \\ t, \textit{Mem} \rightarrow_{\textit{seq}} t', \textit{Mem'} \\ \hline \hline \{\dots, t_i, \dots\}, \textit{Mem} \rightarrow_{\textit{inter}} \{\dots, t'_i, \dots\}, \textit{Mem'} \end{array}$$

<u>Problem</u> : This semantics is incomplete with respect to the Java Memory Model, **unless you write well-synchronized programs**

Natural hypothesis : sequential consistency Intuivively, **sequential consistency** means that all executions respect the program order.



Problem : enforcing sequential consistency for all Java programs makes many of the compiler/processor optimizations illegal.

Why? some optimizations assume well-synchronized programs!

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Example : code reordering (cache mechanisms,...)

Original code Optimized code

C.f = C.g = 0 1: x = C.g; | 3: y = C.f; 2: C.f = 1; | 4: C.g = 1; $\{Perm(1,2,3,4) | 1 < 2, 3 < 4\}$

$$C.f = C.g = 0$$

2: C.f = 1; | 4: C.g = 1;
1: x = C.g; | 3: y = C.f;
{Perm(1,2,3,4) | 2 < 1, 4 < 3}





Java's memory model is weak memory model

All executions of well-synchronized programs are sequentially consistent ^a.

^aManson, Pugh & Adve : The Java Memory Model (Special Popl issue)

Programs must be well-synchronyzed several static analysis depend on it

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Well-synchronized programs

 (P_1) : For all execution (w.r.t the interleaving semantics), every conflicting actions *a* and *b* are synchronized



compiler/jvm/jit : (P_1) \Rightarrow every exec. is captured by the inter. sem.

Happens-before relation

 $\prec_{\textit{hb}}$ is the transitive closure of the following rules :

- sequentiality $a^t \prec^1_{hb} b^t$
- start/join synchronisation

$$\begin{cases} t.\texttt{start}() \prec^1_{hb} a^t \\ a^t \prec^1_{hb} t.\texttt{join}() \end{cases}$$

Iock-based synchronisation

$$\begin{cases} \text{unlock}(m) \prec^{1}_{hb} \text{lock}(m) \\ \text{write}(x.f) \prec^{1}_{hb} \text{read}(x.f) \qquad (f \text{ volatile}) \end{cases}$$

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Data races

definition (JMM) : a program has a data race is there exists an execution with two conflicting actions not not ordered by \prec_{hb} .

alternative definition : a program has a data race if there exists an execution such that, at some point, there is a non deterministic choice (interleaving semantics) among two conflicting actions.

Problem (undecidable) :

Given a program, are all executions of that program race free?

Static detection of data races

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RCC Java

[PLDI'00] Type-based race detection for Java (Flanagan and Freund)

- supports classes parameterized by locks of given types (Dependent types)
- introduce a notion of thread local classes
- Fields protected by locks (static fields)
- Encapsulation : self-protected class
- Extend previous work based on a simple thread calculus

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Example

```
class A(ghost Object x){
     Object y = \text{new Object}() guarded_by x;
      void set(Object z) requires x{
           this.v = z:
class B{
     final Object z = \text{new Object}();
     A\langle this.z \rangle x = \text{new } A\langle this.z \rangle();
     void f(){
          synchronized(this.z){set(new Object())}
```

Ownership types

[OOPSLA'02] Ownership types for safe programming : preventing data races and deadlocks (Boyapati, Lee and Rinard)

Basic idea

Write generic code and create different instance with different protection mechanisms.

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Ownership types

Ownership types Each object is owned by { another object (final field) itself (self) a thread (thisThread)

class $C(Owner_0, Owner_1, \ldots) = \{\ldots \text{new } D(Owner_1)() \ldots\}$

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Static analysis

- The ownership relation builds a forest of trees
- The fields of an object must be protected by the ancester of this object (a root, i.e. an object protected by itself or a thread)

Extensions

support for read-only/single pointer objects

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Ownership types

Example

```
class Account(thisOwner){
    int balance = 0;
    void deposit(int x) requires thisOwner{
        this.balance = this.balance + x;
    }
}
Account (thisThread) a1 = new Account(thisThread)
a1.deposit(10);
```

final Account(self) a2 = new Account(self);
fork{synchronized(a2){a2.deposit(10); }}

```
Account\langle a_2 \rangle a3 = new Account\langle a_2 \rangle;
```

Type inference

[VMCAI'04] Type Inference for Parameterized Race-Free Java (Agarwal and Stoller)

idea :

- Perform a set of execution
- Extract types from this set
- Check types

problem : incomplete

[SAS'04, SCP'07] Type inference against races (Flanagan and Freund)

- consider parameterization of classes as introduced by Boyapati,Lee and Rinard
- by reduction of the problem of finding a satisfying assignment for a boolean formula (NP-complete)

[Sigplan Not.] A type system for preventing data races and deadlocks in the java virtual machine language (Permandla, Roberson, Boyapati)

problem : monitorenter/monitorexit replace synchronized blocks
solution : use indexed types to recover structured locking

Indexed types : [TCS'03] A type system for JVM threads (Laneve) very simple alias analysis

$$i: \texttt{Load} \; \texttt{n}, \{\ldots \textit{n} \mapsto au \ldots\}, \textit{stack} - > \{\ldots \textit{n} \mapsto au_i \ldots\}, au_i:: \textit{stack}$$

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Limitations of type-based approaches

- very strict lock-based discipline
- can't handle other synchronization patterns

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23 / 33

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Language

$$\begin{array}{rll} s & ::= & \mid x = \texttt{null} \mid x = \texttt{new} \ h \\ & \mid x = y \mid x = y.f \mid x.f = y \\ & \mid s_1; s_2 \mid \texttt{if} \ (*) \ \texttt{then} \ s_1 \ \textit{else} \ s_2 \mid \texttt{while}^w \ (*) \ \texttt{do} \ s \end{array}$$

 $\begin{array}{ll} h & \text{allocation site} \\ w \in \mathbb{W} & \text{loop counter} \end{array}$

 $\begin{array}{l} \begin{array}{l} \begin{array}{c} \begin{array}{c} \begin{array}{c} \text{Dynamic semantics} \\ \end{array} \\ Obj ::= \langle h, \pi \rangle & \pi : \mathbb{W} \rightarrow \mathbb{N} \\ C ::= \{ \ldots Obj \rhd Obj' \ldots \} \end{array}$

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Conditional Must Not Aliasing

$$\begin{array}{c|c} \text{synchronized}(x) \{ \\ x.f.g = *; \\ \} \end{array} \quad \begin{array}{c|c} \text{synchronized}(y) \{ \\ y.f.g = *; \\ \} \end{array}$$

 $\frac{\text{Conditional Must Not Aliasing}}{\text{must_not_alias}(x, y) \Rightarrow \text{must_not_alias}(x, f, y, f)}$

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25 / 33

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Disjoint Reachability

$$h \in DR_{C}(H) \Leftrightarrow \begin{cases} \frac{\text{Disjoint reachability}}{\overline{o_{1}}.h \in H \land (\overline{o_{1}} \triangleright \overline{o}) \in C^{+} \land \\ \overline{o_{2}}.h \in H \land (\overline{o_{2}} \triangleright \overline{o}) \in C^{+} \land \\ \overline{o}.h = h \end{cases} \Rightarrow \overline{o_{1}} = \overline{o_{2}}$$

$$\begin{array}{c|ccc} Obj & ::= & \langle \hat{h}, \Pi \rangle \\ \hat{h} & ::= & h \mid \top \\ \Pi & : & \mathbb{W} \mapsto \mathbb{N}_{\top} \\ \mathbb{N}_{\top} & = & \{0, 1, \top\} \end{array} \end{array} \begin{array}{c|cccc} Abstraction \\ \Pi(w) = 0 & w \text{ not active} \\ \Pi(w) = \top & w \text{ unknown} \\ \Pi(w) = \Pi'(w) = 1 & \text{same iteration} \end{array}$$

Judgments : $W, \Pi, \Gamma \vdash s : \Gamma', K$

 $h \in DR_{\mathcal{K}}(H)$ $DR_{\mathcal{K}}(H)$ is a safe appr. of $DR_{\mathcal{C}}(H)$

Disjoint reachability

Examples

 $h_2 \in DR_{\kappa}(\{h_1\})?$ while¹ (*){ while¹ (*){ while¹ (*){ $x = \text{new } h_1;$ $y = \text{new } h_2;$ while² (*){ while² (*){ $x = \text{new } h_1;$ $y = \text{new } h_2;$ $y = \text{new } h_2;$ $x = \text{new } h_1;$ x.f = y;x.f = y;x f = y $YES: \{\langle h_1, (1) \rangle \triangleright$ $\langle h_2, (1) \rangle$ *YES* : { $\langle h_1, (1,0) \rangle$ *NO* : { $\langle h_1, (1,1) \rangle$ $\triangleright \langle h_2, (1,1) \rangle \}$ $\triangleright \langle h_2, (1,0) \rangle \}$

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$$W, \Pi, \Gamma \vdash x = new \ h : \Gamma[x \mapsto \langle \Pi', h \rangle], \emptyset$$

$$W, \Pi, \Gamma \vdash x = y : \Gamma[x \mapsto \Gamma(y)] \qquad W, \Pi, \Gamma \vdash x.f = y, \Gamma, K$$

$$W, \Pi, \Gamma \vdash x = y.f : \Gamma[x \mapsto \langle \lambda w. \top, \top \rangle], \emptyset$$

$$\frac{W, \Pi, \Gamma \vdash s_1 : \Gamma', K_1 \qquad W, \Pi, \Gamma' \vdash s_1 : \Gamma'', K_2}{W, \Pi, \Gamma \vdash s_1; s_2 : \Gamma'', K_1 \cup K_2}$$

$$\frac{W, \Pi, \Gamma \vdash s_1 : \Gamma_1, K_1 \qquad W, \Pi, \Gamma \vdash s_1 : \Gamma_2, K_2}{W, \Pi, \Gamma \vdash \text{ if } (*) \text{ then } s_1 \text{ else } s_2 : \Gamma_1 \sqcup \Gamma_2, K_1 \cup K_2}$$

$$\frac{W \cup \{w\}, \Pi, \Gamma^{w^+} \vdash s : \Gamma, K \qquad \Pi(w) \neq 0}{W, \Pi, \Gamma \vdash while^w \ (*) \text{ do } s : \Gamma, K}$$

Conflicting pairs elimination

Static analysis

- Call graph construction and context-sensitive points-to analysis
- Type and effect system

Conflicting pairs elimination



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Static race detection

30 / 33

Soundness

- reflection
- dynamic loading
- native methods
- libraries ? ? ?

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Conclusion and ongoing work

- Data races detection is important
- Objects offer a good framework
- Type systems can handle strict lock-based discipline but lack more elaborated synchronisation patterns
- Points-to analysis can give very precise results but is much more complex

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Conclusion and ongoing work

Ongoing work Certification of a static analysis for data race detection in Coq

Context-sensitive points-to analysis

• Certification of a result checker in Coq

Static analysis for data race detection

- Formalisation of aiken's type and effect system for Java Bytecode
- Formalisation of successive stages
- Certification in Coq

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